#### Markov-chain Monte Carlo: A modern primer Lecture 1: Fundamentals Part 1/2: MCMC—from balance to lifting

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#### References

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## Direct sampling (1/1)



#### • Distribution $\pi =$ uniform in square

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## Markov-chain sampling (1/2)



• Distribution  $\pi =$  uniform in heliport square

## Markov-chain sampling (2/2)



• Metropolis et al. (1953).

# Transition matrix (1/4)

discretized version of heliport game







# Transition matrix (2/4)

Transition-matrix element P<sub>ij</sub>: probability to move to j if at i:



All *P* are stochastic matrices: *P<sub>ij</sub>* ≥ 0, ∑<sub>j</sub> *P<sub>ij</sub>* = 1
The pebble-game *P* is doubly stochastic.

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## Transition matrix (3/4)

• Initial distribution (NB: row vector)

$$\pi^{\{t=0\}} = \{0, \dots, 0, 1\}.$$

• Distribution at time t + 1 (short hand:  $\pi^{\{t+1\}} = \pi^{\{t\}} P$ )

$$\pi_{i}^{\{t+1\}} = \sum_{j=1}^{9} \pi_{j}^{\{t\}} P_{j \to i}$$

NB: *P* connects samples  $x_{t+1}$  to  $x_t$ , but also  $\pi^{\{t+1\}}$  to  $\pi^{\{t\}}$ 

• Left eigenvectors, eigenvalues

$$\{\pi_1^{\{t\}}, \dots, \pi_9^{\{t\}}\} = \underbrace{\{\frac{1}{9}, \dots, \frac{1}{9}\}}_{\text{first left eigenvector}} + \alpha_2(0.75)^t \underbrace{\{-0.21, \dots, 0.21\}}_{\substack{\text{second left eigenvector}\\ \text{eigenvalue } \lambda_1 = 1}} + \dots$$

## Transition matrix (4/4)

- Heliport square  $\rightarrow$  sample space  $\Omega$ .
- Players  $\rightarrow$  Markov chain: Sequence of random variables  $(X_0, X_1, ...)$  where  $X_0$  represents the initial distribution and  $X_{t+1}$  depends on  $X_t$  through P.
- Four-arrow star  $\rightarrow$  split matrix:  $P_{ij} = A_{ij}P_{ij}$  $A \Leftrightarrow a \text{ priori}$  probability;  $P \Leftrightarrow$  filter Examples: Metropolis filter, heatbath filter.
- Pebble piles → P<sub>ii</sub> ⇔ (filter) rejection probability.
   NB: Modern MCMC algorithms often have no rejections.
- Eigensystem analysis → Not always possible

## Irreducibility

- *P* irreducible  $\Leftrightarrow$  any *i* can be reached from any *j*.
- $\pi^{\{0\}}$ : Initial probability (user-supplied). If concentrated on a single initial configuration:  $\pi^{\{0\}}$  is a (Kronecker)  $\delta$ -function.
- *P* irreducible  $\Rightarrow$  unique *stationary distribution*  $\pi$  with

$$\pi_i = \sum_{j \in \Omega} \pi_j \boldsymbol{P}_{ji} \quad \forall i \in \Omega.$$

• No guarantee that  $\pi^{\{t\}} \to \pi$  for  $t \to \infty$ , for any  $\pi^{\{0\}}$ 

#### Ergodic theorem

- *P* irreducible  $\Rightarrow \pi$  unique, but maybe  $\pi^{\{t\}} \not\to \pi$  for  $t \to \infty$ .
- *P* irreducible  $\Rightarrow$  Ergodic theorem ( $\mathbb{E}(\mathcal{O}) := \sum_{i \in \Omega} \mathcal{O}_i \pi_i$ ):

$$P_{\pi^{\{0\}}}\left[\lim_{t\to\infty}\frac{1}{t}\sum_{i_t}\mathcal{O}(i_t)=\mathbb{E}\left(\mathcal{O}\right)\right]=1$$

(Strong law of large numbers for a single running average)



### **Probability flows**

• Uniqueness of  $\pi \Rightarrow$  balance condition on *P*:

$$\pi_i = \sum_{j \in \Omega} \pi_j P_{ji} \quad \forall i \in \Omega.$$

• "flow" from *j* to  $i \Leftrightarrow$  probability  $\times$  probability to move:

$$\mathcal{F}_{ji} \equiv \pi_j \mathcal{P}_{ji} \quad \Leftrightarrow \pi_i = \underbrace{\sum_{j \in \Omega} \mathcal{F}_{ji}}_{j \in \Omega} \quad \forall i \in \Omega,$$
  
flows exiting *i* flows entering *i*  
$$\mathcal{F}_{ji} \equiv \pi_j \mathcal{P}_{ji} \quad \Leftrightarrow \underbrace{\sum_{k \in \Omega} \mathcal{F}_{ik}}_{k \in \Omega} = \underbrace{\sum_{j \in \Omega} \mathcal{F}_{ji}}_{j \in \Omega} \quad \forall i \in \Omega,$$

(NB: stochasticity condition used  $\sum_{k \in \Omega} P_{ik} = 1$ ).

- Set of return times at configuration *i*: {*t* ≥ 1 : (*P<sup>t</sup>*)<sub>*ii*</sub> > 0}
- $\{2, 4, 6, \dots\} \Rightarrow$  period is 2
- $\{1000, 1001, 1002, \dots\} \Rightarrow \text{period is } 1$
- Period = 1: ⇔ Markov chain is aperiodic
- For irreducible, aperiodic P: P<sup>t</sup> = (P<sup>t</sup>)<sub>ij</sub> is a positive matrix for some fixed t.
- For irreducible, aperiodic *P*: exponential convergence towards π from any starting distribution π<sup>{0}</sup>.

### Reversibility

• Reversible *P* satisfies the "detailed-balance" condition:

$$\underbrace{\pi_i P_{ij}}_{\mathcal{F}_{ij}} = \underbrace{\pi_j P_{ji}}_{\mathcal{F}_{ji}} \quad \forall i, j \in \Omega.$$

• General P satisfies "global-balance" condition

$$\pi_i = \sum_{j \in \Omega} \pi_j \boldsymbol{P}_{ji} \quad \forall i \in \Omega.$$

- Detailed balance implies global balance.
- Global balance:

flows exiting *i* flows entering *i*  

$$\overbrace{k\in\Omega}^{\mathcal{F}_{ik}}\mathcal{F}_{ik} = \overbrace{j\in\Omega}^{\mathcal{F}_{ji}}\mathcal{F}_{ji} \quad \forall i\in\Omega.$$

• DBC more restrictive, but far easier to check than GBC.

#### Spectrum of reversible transition matrix

• Reversible P:

$$\pi_i \boldsymbol{P}_{ij} = \pi_j \boldsymbol{P}_{ji} \quad \forall i, j \in \Omega.$$

- Reversible *P*:  $A_{ij} = \pi_i^{1/2} P_{ij} \pi_j^{-1/2}$  is symmetric.
- Reversible P:

$$\sum_{j\in\Omega}\underbrace{\pi_i^{1/2}P_{ij}\pi_j^{-1/2}}_{A_{ij}}x_j = \lambda x_i \Leftrightarrow \sum_{j\in\Omega}P_{ij}\left[\pi_j^{-1/2}x_j\right] = \lambda\left[\pi_i^{-1/2}x_i\right].$$

- P and A have same eigenvalues.
- A symmetric: (Spectral theorem): All eigenvalues real, can expand on eigenvectors.
- Irreducible, aperiodic: Single eigenvalue with λ = 1, all others smaller in absolute value.

Non-reversible *P* can be "unhappy" in different ways:

- *P* can be non-reversible, real eigenvalues, eigenvectors non-orthogonal.
- P can be non-reversible, real eigenvalues: Non-diagonalizable. (algebraic multiplicity ≠ geometric multiplicity).
- *P* can be non-reversible, pairs of complex eigenvalues.

#### Total variation distance, mixing time

Total variation distance:

$$||\pi^{\{t\}} - \pi||_{\mathsf{TV}} = \max_{A \subset \Omega} |\pi^{\{t\}}(A) - \pi(A)| = \frac{1}{2} \sum_{i \in \Omega} |\pi_i^{\{t\}} - \pi_i|.$$

- (Above) first eq.: definition; second eq.: (tiny) theorem
- Distance:

$$d(t) = \max_{\pi^{\{0\}}} ||\pi^{\{t\}}(\pi^{\{0\}}) - \pi||_{\mathsf{TV}}$$

Mixing time:

$$t_{\min}(\epsilon) = \min\{t : d(t) \le \epsilon\}$$

• Usually  $\epsilon = 1/4$  is taken (arbitrary, must be smaller than  $\frac{1}{2}$ ):  $t_{\text{mix}} = t_{\text{mix}}(1/4)$ 

- Graph diameter *L*: minimum number of moves to travel between any *i*, *j* ∈ Ω.
   NB: *L* = 4 for 3 × 3 pebble game.
- Diameter bound: for any  $\epsilon < 1/2$ , trivially satisfies

 $t_{\rm mix} \ge L/2.$ 

#### Conductance (bottleneck ratio) (1/5)



#### Conductance (bottleneck ratio) (2/5)



#### NB: ... this is less efficient than direct sampling

#### Conductance (bottleneck ratio) (3/5)



NB: ... reaches a boundary site  $i \in \partial S$  with probability  $\pi_i / \pi_S$ 

### Conductance (bottleneck ratio) (4/5)



NB: ... reaches a boundary site  $i \in \partial S$  with probability  $\leq \pi_i / \pi_S$ 

## Conductance (bottleneck ratio) (5/5)

$$\Phi \equiv \min_{\mathcal{S} \subset \Omega, \pi_{\mathcal{S}} \leq \frac{1}{2}} \frac{\mathcal{F}_{\mathcal{S} \to \overline{\mathcal{S}}}}{\pi_{\mathcal{S}}} = \min_{\mathcal{S} \subset \Omega, \pi_{\mathcal{S}} \leq \frac{1}{2}} \frac{\sum_{i \in \mathcal{S}, j \notin \mathcal{S}} \pi_i P_{ij}}{\pi_{\mathcal{S}}}.$$

Reversible Markov chains:

$$rac{\mathsf{const}}{\Phi} \leq au_{\mathsf{corr}} \leq rac{\mathsf{const}'}{\Phi^2}$$

("≤": Sinclair & Jerrum (1986), Lemma (3.3))

Mixing-time bounds:

$$rac{ ext{const}}{\Phi} \leq \textit{t}_{ ext{mix}} \leq rac{ ext{const}'}{\Phi^2} \log\left(1/\pi_0
ight)$$

const and const' depend on whether reversible or non-reversible. π<sub>0</sub>: smallest weight (see Chen et al 1999).
NB: One bottleneck, not many. Lower *and* upper bound.

# Lifting (Chen et al (1999)) (1/2)

- Markov chain  $\Pi \Leftrightarrow$  Lifted Markov chain  $\widehat{\Pi}$
- $\Omega \ni v$  (sample space)  $\Leftrightarrow \widehat{\Omega} \ni i$  (lifted sample space)
- *P* (transition matrix)  $\Leftrightarrow \widehat{P}$  (lifted transition matrix)
- $\pi_{\nu}$  (stationary probability)  $\Leftrightarrow \hat{\pi}_i$
- Condition 1: sample space is copied ("lifted"),  $\pi$  preserved

$$\pi_{\boldsymbol{v}} = \hat{\pi}\left[f^{-1}(\boldsymbol{v})\right] = \sum_{i \in f^{-1}(\boldsymbol{v})} \hat{\pi}_i,$$

Condition 2: flows are preserved

$$\underbrace{\pi_{v} P_{vu}}_{\text{collapsed flow}} = \sum_{i \in f^{-1}(v), j \in f^{-1}(u)} \widehat{\pi_{i} \widehat{P}_{ij}}$$

• Usually:  $\widehat{\Omega} = \Omega \times \mathcal{L}$ , with  $\mathcal{L}$  a set of lifting variables  $\sigma$ 

# Lifting (Chen et al (1999)) (2/2)

- Required: Mapping from Ω (lifted sample space) to Ω that preserves stationary probability distribution.
- Required: Lifted transition matrix  $\hat{P}$  that preserves flow.
- Optional:  $\widehat{\Omega} = \Omega \times \mathcal{L}$  (with  $\mathcal{L}$ : set of lifting variables).
- Optional:

$$\frac{\hat{\pi}(\boldsymbol{u},\sigma)}{\pi(\boldsymbol{u})} = \frac{\hat{\pi}(\boldsymbol{v},\sigma)}{\pi(\boldsymbol{v})} \quad \forall \ \boldsymbol{u}, \boldsymbol{v} \in \Omega; \forall \ \sigma \in \mathcal{L}.$$
(1)

- There are many liftings  $\widehat{P}$  for a given lifted sample space  $\widehat{\Omega}$ .
- Liftings are popular for transfering parts of the moves into the sample space.
- Lifting do not increase conductance.